# On the Formal Definition of Separation-of-Duty Policies and their Composition

Virgil D. Gligor Electrical Engineering Department University of Maryland College Park, MD. 20742 Serban I. Gavrila VDG Inc. 6009 Brookside Drive Chevy Chase, MD. 20815 David Ferraiolo NIST U.S. Dept. of Commerce Gaithersburg, MD. 20798

#### Abstract

In this paper we define formally a wide variety of separation-of-duty (SoD) properties, which include the best known to date, and establish their relationships within a formal model of role-based access control (RBAC). The formalism helps remove all ambiguities of informal definition, and offers a wide choice of implementation strategies. We also explore the composability of SoD properties and policies under a simple criterion. We conclude that practical implementation for SoD policies requires new methods and tools for security administration even within applications that already support RBAC, such as most database management systems.

### 1 Introduction

As a security principle, separation of duty (SoD) has had wide application in business, industry, and government [3, 4, 7]. Its purpose is to ensure that failures of omission or commission within an organization are caused only by collusion among individuals and, therefore, are riskier and less likely, and that chances of collusion are minimized by assigning individuals of different skills or divergent interests to separate tasks. For example, SoD is enacted whenever conflict of interest may otherwise arise in assignment of tasks within an organization.

As an application-design principle, SoD requires the following three well-understood design and implementation steps:

Integrity Property Definition. Within an application domain, the aim of SoD is defined by integrity properties. These properties may require that each application include independent, redundant functions whose results must match to enable a sensitive task (e.g., the results of two orthogonal single-entry accounting activities must match; two persons must approve the execution of an action such

as signing a check, installing a crypto key, or launching a missile). Or, they may require that an application enact conflict-of-interest resolution by establishing balances and checks among its tasks (e.g., different users are required to perform asset accounting and control, or system security administration and auditing).

Application Design. The objects and operations of an application subject to SoD are partitioned to implement, maintain, and verify the integrity properties. For example, application partitioning may separate the operations that perform accounts-payable, purchasing, and payroll tasks. It may further separate check reading/writing from signing operations within both accounts-payable and payroll tasks, and purchase-order reading/writing from signing operations within purchasing tasks.

User Assignment to Application Partitions. Users of different skills or interests are assigned to operate in different application partitions. These assignments may last for limited periods of time, and may change dynamically. By performing such assignments, application administration ensures that user collusion is required to breach integrity properties, and that chances of collusion are minimized.

Despite its importance as a security principle and its well-understood application in business, industry, and government, few computer systems have supported SoD as a security policy to date [10, 15]. We attribute the lack of wide-spread support to three separate reasons. First, SoD is an inherently application-oriented policy and, thus, has been perceived to yield limited payoff for operating systems and networks, since it cannot be used as a global, system-wide security policy. Second, when the SoD principle is interpreted within different applications, it may yield many different SoD policies and, thus, support of all policies is perceived to require both substantial system flexibility [15] and recurrent administrative costs -- an unmistakable recipe for both system-vendor and market resistance in the absence of advanced policy-administration tools. Third, most SoD policies proposed to date have been only informally

defined and, therefore, subject to ambiguous or incomplete specifications, and limited assurance. As a consequence, both relationships among SoD properties and policy composability -- an important requirement for all application-oriented policies -- could not be easily established.

The perceived disadvantages of SoD as a family of application-oriented policies can be mitigated by two factors. First, growing interest in internet applications and their security may lead to the development of versatile SoD policies and administrative tools at a cost made reasonable by the economies of scale. Second, better understanding of SoD policies for computer systems via precise, possibly formal, definition may remove the aura of complexity associated with these policies, thereby facilitating their acceptance.

In this paper we define a set of SoD policies (Sections 2 and 4), which includes the best-known ones [15], and establish their relationships within a formal model of role-based access control (RBAC) [8]. The formalism (Sections 3 and 4) helps remove ambiguities of informal definition and offers a wide choice of implementation strategies. We also explore the composability of these policies under a simple criterion, and identify classes of policies that are, or are not, composable (Section 5). We conclude (Section 6) that practical implementation for SoD policies requires new methods and tools for security administration, even within applications that support RBAC, such as most database management systems [12].

# 2 Specification of SoD Policies

In this section, we define the structure of a SoD policy as a conjunction of constituent properties (or predicates) of system states and state transitions, or of command sequences (or traces) executed by systems. To view security policies as conjunctions of properties is appealing because it helps determine security-policy effectiveness [11] -- by assigning each property a role in countering a threat -- and relative strength -- by (partially) ordering the threats countered by policy properties. However, we adopt this view because we are interested in defining security policies by property composition. This allows us to use similar composition criteria for incremental property addition to, removal from, or modification of extant policies. For example, we define SoD policies both by incremental addition of new properties to conjunctions of RBAC properties and by composing extant SoD policies.

#### 2.1 Dependencies Among Policy Properties

Although viewing security policies as compositions of security properties (i.e., by conjunction) is appealing, care must be exercised because the composition of independent security properties does not necessarily define a policy. The reason for this is that the properties of a policy are not independent; i.e., both individual and groups of properties may depend on other properties of the conjunction to counter a specific set of threats. Ignoring dependencies among policy properties has undesirable effects<sup>1</sup>. For example, the inadvertent omission or incorrect modification of any property that is depended upon by others may cause the policy to become ineffective, undefined or incorrectly defined, or empty. Furthermore, analysis of policy effectiveness, relative strength, and composability may yield inconsistent or incorrect results without analysis of dependencies. In Section 5, we show that property omission can cause policies which are otherwise not composable to appear to be composable. (For similar reasons, the identification of dependencies among the properties of cryptographic protocols is also considered important [11].)

To illustrate the notion of dependency among policy properties, consider the following three types of properties: access-attribute (AT), access-authorization (AA), and access-management (AM) properties. Access attributes include subject and object attributes (e.g., user, group, role, location identifiers, secrecy and integrity levels, time-of-access intervals), and AT properties typically establish invariant relationships among attributes (e.g., lattices of secrecy and integrity levels, user-group membership invariants, inheritance of role permissions). AA properties determine whether a subject's current access attributes satisfy the conditions for accessing an object given the current object attributes. In contrast, AM properties include conditions under which subjects are granted or revoked attributes for accessing objects, subjects and objects are created or destroyed, objects are encapsulated within protected subsystems. In general, AM properties characterize commands and constraints that bring the system to desired states, whereas AA properties characterize constraints that ensure that the system remains in desired states.

<sup>&</sup>lt;sup>1</sup> The notion of dependency among the policy properties (a.k.a. dependencies among policy "functional" requirements) is neither new nor novel. It has already received extensive coverage in the security-standards literature [5, 6, 17] where templates for defining policy properties are provided to enable policy analysis and evaluation.

A typical dependency arises between AA and AM properties because the values of the attributes used by the former for access decisions are determined by the latter (i.e., AA properties have a "uses" dependency on AM properties). Hence, whether an AA property holds in a state depends not only on the property (predicate) itself but also on the defined AM properties. Both AA and AM properties have "uses" dependencies on AT properties. Furthermore, AM properties also have "uses" dependencies on AA properties whenever object attributes themselves are treated as objects and, hence, become the target of access authorization. Techniques to redefine policy properties to avoid this cyclic dependency, and other undesirable ones, are presented elsewhere [6].

Groups of policy properties may also depend upon individual properties used in the same conjunction. For example, the property  $P = AT \land AA \land AM$ , depends on an AM property, denoted by Admin(P), which requires that administrative commands have the ability to bring the system from an arbitrary state to a state (or any state) that satisfies P. Admin(P) is formally defined in Section 5. Unless Admin(P) is satisfied, the policy defined by property P is empty because the system operating under P can neither start from, or recover to, a secure state [16] nor reach a secure state from another secure state under administrative control.

For application-oriented policies, such as SoD, the composition of independent security properties does not necessarily define a usable policy. To be useful, property  $P = AT \wedge AA \wedge AM$  must be compatible with the application for which it was designed. Informally, this means that P may not unjustifiably deny the execution of the application; e.g., an AM property should not grant users too few, or inconsistent, permissions for application execution. This property, denoted by Compat(P, App), where App is the application, is formally defined in Section 5.

## 2.2 Structure of SoD Policies in RBAC Systems

A security policy  $\mathcal{P}$  can be defined as:  $\mathcal{P} = P \wedge Admin(P),$ 

where  $P = AT \wedge AA \wedge AM$ . The property P itself may have other properties in addition to Admin(P); e.g., application-oriented policies, such as SoD, also include property Compat(P, App). We specify SoD policies as incremental conjunctions of properties to RBAC policies. That is,

 $\mathcal{S} \circ \mathcal{D} - \mathcal{P} = SoD - P \wedge Admin(SoD - P) \wedge Compat(SoD - P, App)$ 

^ RBAC-P

where  $\mathcal{RBAC-P} = RBAC-P \wedge Admin(RBAC-P)$ , and both SoD-P and RBAC-P are conjunctions of AT, AM, and AA

properties. Some, but not all, properties of *SoD-P* may be empty.

The specification of SoD policies as incremental additions of specific properties to RBAC policies is both useful and justified in practice. It is useful because a large number of properties that are common to all SoD policies are part of RBAC models. For example, RBAC formal models [8] include both flexible AA and AM properties and, hence, AM and AA properties of SoD can be defined as incremental properties (i.e., predicates on the types, functions, states, and state transitions) of RBAC. In practice, most SoD policies are implemented atop systems that support RBAC policies. RBAC enables the partitioning of application operations and objects, and also the selective assignment of roles to application operations and users (two of the key steps in SoD policy design presented in Section 1).

### 3 Secure RBAC Systems and Applications

In this section we define the types, functions, and properties of a RBAC system that are necessary to define SoD properties. The formal RBAC model, which consists of a conjunction of RBAC policy properties, is presented elsewhere [8].

We consider a RBAC system to be defined by a state machine model. We denote the set of system states by STATES, the set of subjects by SUBJECTS, the set of users by USERS, the set of operations by OPERATIONS, and the set of objects by OBJECTS. A RBAC system is characterized by the fact that a user's rights to access objects are defined by the user's membership to a "role" and by the roles' permissions to perform operations on those objects. Hence, a role is a collection of operations on object sets. The class of roles, ROLES, is a subset of

 $2^{OPERATIONS \times 2^{ORJECTS}}$ . The function

auth:  $STATES \times ROLES \times OBJECTS \rightarrow 2^{OPERATIONS}$ 

defines the operations allowed to each role in each state of the system:

 $\forall s \in STATES, \forall op \in OPERATIONS, \forall r \in ROLES,$ 

 $\forall obj \in OBJECTS, op \in auth(s, r, obj) \Leftrightarrow$ 

 $\exists objset \subseteq OBJECTS: obj \in objset \land (op, objset) \in r.$ 

The function  $role\_members:ROLES \rightarrow 2^{USERS}$  defines the users assigned to a given role.

The function  $subject\_user: SUBJECTS \rightarrow USERS$  returns the user associated with the subject.

The function

subject roles: $STATES \times SUBJECTS \rightarrow 2^{ROLES}$ 

returns the roles assumed by a user in a given state while executing a given subject. These roles must have been assigned to the subject's user.

The function  $current\_role\_set:STATES \times USERS \rightarrow 2^{ROLES}$  is defined as follows:  $\forall s \in STATES, \forall u \in USERS,$   $current\_role\_set(s, u) = \bigcup_{S \in SUBJECT} subject\_roles(S).$ 

If  $r \in current\_role\_set(s, u)$ , then we say that the role r is enabled or active for the user u in state s.

Each state transition is defined by a command of the form  $op(s_1, S, obj, s_2)$ , where the subject S performs the operation op on the object or objects denoted by obj, thereby changing the system state from  $s_1$  to  $s_2$ . Access authorization in RBAC requires that the state transition  $op(s_1, S, obj, s_2)$  take place only if at least one of the roles in  $subject\_roles(s_1, S)$  has the permission to perform the operation op on the object, or objects, obj. Formally,  $op(s_1, S, obj, s_2) \Rightarrow$ 

 $\exists r \in subject \ roles(s_1, S): op \in auth(s_1, r, obj).$ 

A command sequence is  $op_1(s_0, S_1, obj, s_1) \cdot op_2(s_1, S_2, obj_2, s_2) \cdot ...$ , where "." is the concatenation operator, and  $s_0$  is the start state. We denote the set of start states of a command sequence by  $STATES_0$ . A finite command sequence  $\sigma$  may be extended to an infinite one by adding "no-op" commands, that do nothing and preserve the system state.  $\hat{\sigma}$  denotes the extended command sequence. If  $s_0$  is a start state,  $\hat{s}_0$  denotes the command sequence starting in  $s_0$  and consisting only of no-op commands. We denote the set of command sequences of a system with the start states in  $STATES_0$  by  $\Omega_0$ . Whenever  $STATES_0 = STATES$ , we drop the subscript " $_0$ ".

A tranquil command is a command that does not alter the security attributes/data of the system (e.g., creation, deletion, or update of roles). A tranquil command sequence is a command sequence consisting only of tranquil commands. We denote the set of tranquil command sequences of a system with the start states in  $STATES_0$  by  $\Sigma_0$ . Whenever  $STATES_0 = STATES$ , we drop the subscript " $_0$ ".

A secure state is a state that satisfies some "state" properties. A secure command is a command that satisfies some "transition" properties. A reachable state is a state appearing in a command sequence. A system is secure if all its reachable states are secure and all commands used in its command sequences are secure. In this paper, we consider only secure RBAC systems.

The partial function:  $access\_history$ :  $STATES \times STATES \times USERS \times 2^{ROLES} \times OBJECTS \rightarrow 2^{OPERATIONS}$ 

returns the operations performed by RBAC users in all states between  $s_0$  and s, where state s is reachable from state  $s_0$ . It has the following properties:

```
\begin{aligned} 1. \, \forall s \in STATES, \, \forall u \in USERS, \, \forall r \in ROLES, \\ \forall obj \in OBJECTS, \, access\_history(s, s, u, \{r\}, obj) = \varnothing. \\ 2. \, \forall s_0, s \in STATES, \, \forall u \in USERS, \, \forall roleset \subseteq ROLES, \\ \forall obj \in OBJECTS, \, access\_history(s_0, s, u, roleset, obj) = \\ & \cup \quad access\_history(s_0, s, u, \{r\}, obj). \\ 3. \, \forall s_0, s_1, s_2 \in STATES, \, \forall op \in OPERATIONS, \\ \forall S \in SUBJECTS, \, \forall u \in USERS, \, \forall r \in ROLES, \\ op(s_1, S, obj, s_2) \land subject\_user(S) = u \land \\ r \in subject\_roles(S) \Rightarrow \\ access\_history(s_0, s_2, u, \{r\}, obj) = \\ access\_history(s_0, s_1, u, \{r\}, obj) \cup \{op\}. \end{aligned}
```

An application is a tuple App = [ObjSet, OpSet, Plan], where  $ObjSet \subseteq OBJECTS$  and  $OpSet \subseteq OPERATIONS$ . Plan is the execution plan of the application and consists of a finite set of pairs  $\{(obj_i, op_i)|i \in \{1,...,n\}\}$ , where n is a natural number,  $obj_i$  is one or more objects of ObjSet, and  $op_i \in OpSet$ .

Given two applications  $App_i = [ObjSet_i, OpSet_i, Plan_i]$ , i=1, 2, we denote the new application  $[ObjSet_1 \cup ObjSet_2, OpSet_1 \cup OpSet_2, Plan_1 \cup Plan_2]$  by  $App_1 \cup App_2$ .

A command sequence  $\sigma \in \Sigma_0$  executes the application App (App is executed by  $\sigma$ , or  $\sigma$  is an execution of App), if for any pair (obj, op) in the App's execution plan there is a command  $op(s_k, S, obj, s_{k+1})$  in  $\sigma$ . For simplicity, we omit other types of application executions and execution plans; e.g., executions and plans that include order, or that exclude redundant operations and privileges to objects to help satisfy the "least privilege" principle. We also use App to denote the set of all executions  $\sigma$  of App.

A user needs permissions to execute the operations of an application App, and since these permissions as given by roles, the user must assume the necessary roles to execute App. The AM properties of SoD policies specify the assignments of roles to application operations and users.

# 4 SoD Properties in Secure RBAC Systems

In this section, we define a variety of SoD properties, their relationships in secure RBAC systems, and their composition based on property conjunctions. As usual [15], we distinguish between "static" and "dynamic" SoD properties.

Clark and Wilson defined the static SoD by the rule that: "each user must be permitted to use only certain ... transactions" [4]. In a RBAC environment, their definition is expressed as follows:

**Static Separation of Duty (SSoD).** Let App be an application and RoleSet its assigned roles in a secure

RBAC system.  $\sigma \in \Sigma_0$  satisfies the *SSoD* property with respect to *App* if any two distinct roles in *RoleSet* do not have common members. Such roles are said to be *restricted*. Formally,

```
\sigma \in SSoD(RoleSet, App) \Leftrightarrow \forall r_1, r_2 \in RoleSet, r_1 \neq r_2 \Rightarrow role \ members(r_1) \cap role\_members(r_2) = \emptyset.
```

We obtain a stronger version of this property by adding the requirement that the target object sets of two restricted roles be *disjoint*:

Strict Static Separation of Duty (SSSoD). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the SSSoD property with respect to App if any two distinct roles in RoleSet: a) do no have common members, and b) are not authorized to perform operations in OpSet on the same object of the application. Formally:  $\sigma \in SSSoD(RoleSet, App) \Leftrightarrow$ 

```
(\forall s \text{ state of } \sigma, \forall r_1, r_2 \in RoleSet, r_1 \neq r_2 \Rightarrow role\_members(r_1) \cap role\_members(r_2) = \emptyset \land \{o \in ObjSet \mid auth(s, r_1, o) \cap OpSet \neq \emptyset\} \cap \{o \in ObjSet \mid auth(s, r_2, o) \cap OpSet \neq \emptyset\} = \emptyset).
```

We obtain a still stronger version by adding the requirement that each role execute *only one step* (operation) of the application [14]:

1-step Strict Static Separation of Duty (1sSSSoD). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the IsSSSoD property with respect to App if a) any two distinct roles in RoleSet do no have common members; b) any role in RoleSet is authorized to perform at most one operation of OpSet on application's objects; and c) any two distinct roles in RoleSet are not authorized to perform operations in OpSet on the same object of the application. Formally:

```
\sigma \in IsSSSoD(RoleSet, App) \Leftrightarrow \\ (\forall s \text{ state of } \sigma, \forall r, r_1, r_2 \in RoleSet, \forall obj \in ObjSet, \\ |auth(s, r, obj) \cap OpSet| \leq 1 \land \\ (r_1 \neq r_2 \Rightarrow \\ role\_members(r_1) \cap role\_members(r_2) = \emptyset \land \\ \{o \in ObjSet \mid auth(s, r_1, o) \cap OpSet \neq \emptyset\} \cap \\ \{o \in ObjSet \mid auth(s, r_2, o) \cap OpSet \neq \emptyset\} = \emptyset).
```

Clark and Wilson [4], and then others, defined several "dynamic separation of duty" properties. In an RBAC system, a dynamic SoD property with respect to the roles assumed by the users ("active" roles) can be defined as follows [7]:

**Dynamic Separation of Duty (DSoD).** Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the DSoD property with respect to App if, in any

state of  $\sigma$ , there is no user with two distinct roles in RoleSet enabled (active). Formally,

```
\sigma \in DSoD(RoleSet, App) \Leftrightarrow
(\forall s \text{ state of } \sigma, \forall r_1, r_2 \in RoleSet, \forall u \in USERS, r_1 \neq r_2 \land r_1 \in current\_role\_set(s, u) \Rightarrow
r_2 \notin current\_role\_set(s, u)).
```

Nash and Poland [13] introduced the object-based, dynamic SoD, as a more flexible and realistic alternative to the static SoD. However, their informal definition [13, 15] does not specify precisely which objects, operations, roles are subjected to the object-based SoD condition. Our definition removes these ambiguities.

Object-based Dynamic Separation of Duty (ObjDSoD). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the ObjDSoD property with respect to App if, any user which performs an operation in OpSet on an object of ObjSet in a role of RoleSet as a command of  $\sigma$  has not already performed another operation of OpSet on the same object in a role of RoleSet. Formally,

```
\sigma \in ObjDSoD(RoleSet, App) \Leftrightarrow \\ (\forall s_0, s_1, s_2 \in STATES, \forall r \in RoleSet, \forall op \in OpSet, \\ \forall obj \in ObjSet, \forall S \in SUBJECTS, \\ \sigma \text{ starts in } s_0 \land \\ op(s_1, S, obj, s_2) \text{ is in } \sigma \land \\ subject\_roles(s_1, S) \cap RoleSet \neq \emptyset \Rightarrow \\ access\_history(s_0, s_1, subject\_user(S), \{r\}, obj) \cap \\ OpSet \subseteq \{op\}\}.
```

The following two properties are static variants of the object-based dynamic SoD, the first for set of roles with common members, and the second for single roles.

Object-based Static Separation of Duty (ObjSSoD). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the ObjSSoD property with respect to App if, in any state  $\sigma$ , no group of application roles with a common assigned user is authorized to perform more than one operation on each object of the application. Formally,

```
\sigma \in ObjSSoD(RoleSet, App) \Leftrightarrow \\ \forall s \text{ state of } \sigma, \forall RoleSubset \subseteq RoleSet, } \forall op_1, op_2 \in OpSet, \\ \forall obj \in ObjSet, \\ op_1 \neq op_2 \land \bigcap_{r \in RoleSubset} - members(r) \neq \emptyset \Rightarrow \\ \{op_1, op_2\} \nsubseteq \bigcup_{r \in RoleSubset} auth(s, r, obj).
```

Per-Role Object-based Static Separation of Duty (*RObjSSoD*). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the RObjSSoD property with respect to App if, in any state of  $\sigma$ , no role in RoleSet

is authorized to perform more than one operation of *OpSet*. Formally,

```
\sigma \in RObjSSoD(RoleSet, App) \Leftrightarrow
(\forall s \text{ state of } \sigma, \forall r \in RoleSet, \forall op_1, op_2 \in OpSet, \forall obj \in ObjSet, op_1 \neq op_2 \Rightarrow \{op_1, op_2\} \not\subseteq auth(s, r, obj)).
```

Another flexible alternative to static SoD is the operational SoD. The following property is (a corrected version of that) presented by Ferraiolo, Cugini and Kuhn [7]:

Operational Static Separation of Duty (*OpSSoD*). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the OpSSoD property with respect to App if, in any state of  $\sigma$ , any subset of roles in RoleSet with a common member is not authorized to perform all the operations of OpSet (if more than one), regardless of the target object. Formally,

```
\sigma \in OpSSoD(RoleSet, App) \Leftrightarrow \\ \forall s \text{ state of } \sigma, \forall RoleSubset \subseteq RoleSet, \\ |OpSet| \ge 2 \land \bigcap_{r \in RoleSubset} role\_members(r) \neq \emptyset \Rightarrow \\ OpSet \not\subseteq \bigcup_{\substack{r \in RoleSubset \\ obj \in ObjSet}} auth(s, r, obj).
```

The following variant of operational separation of duty is obtained by applying the operational separation of duty to single roles.

**Per-Role Operational Static Separation of Duty** (*ROpSSoD*). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the OpSSoD property with respect to App if, in any state of  $\sigma$ , no application role is authorized to perform all the operations of the application regardless of the target object. Formally,

```
\sigma \in ROpSSoD(RoleSet, App) \Leftrightarrow \forall s \text{ state of } \sigma, \forall r \in RoleSet, \\ |OpSet| \ge 2 \Rightarrow OpSet \not\sqsubseteq \bigcup_{obj \in ObjSet} auth(s, r, obj).
```

Operation separation of duty has the following dynamic variant.

Operational Dynamic Separation of Duty (OpDSoD). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the OpDSoD property with respect to App if, in any state of  $\sigma$ , any subset of roles in RoleSet enabled for the same user is not authorized to perform all the operations of OpSet (if more than one), regardless of the target object. Formally,

```
\sigma \in OpDSoD(RoleSet, App) \Leftrightarrow \forall s \text{ state of } \sigma, \forall u \in USERS, \forall RoleSubset \subseteq RoleSet, |OpSet| \ge 2 \land RoleSubset \subseteq current role set(s, u) \Rightarrow
```

$$OpSet \nsubseteq \bigcup_{\substack{r \in RoleSubset \\ obj \in ObjSet}} auth(s, r, obj).$$

Simon and Zurko [15] have generalized both operational and object-based dynamic separation of duty as the history-based separation of duty. The formal version of their property follows.

History-based Dynamic Separation of Duty (HDSoD). Let App=[ObjSet, OpSet, Plan] be an application and RoleSet its assigned roles in a secure RBAC system.  $\sigma \in \Sigma_0$  satisfies the HDSoD property with respect to App if in  $\sigma$ , the same user cannot perform all the operations in OpSet on the same object of ObjSet in roles assigned to the application. Formally,

```
\sigma \in HDSoD(RoleSet, App) \Leftrightarrow
(\forall s_0, s_1, s_2 \in STATES, \forall op \in OpSet, \forall obj \in ObjSet, \forall S \in SUBJECTS, \forall u \in USERS
\sigma starts in s_0 \land op(s_1, S, obj, s_2) is in \sigma \land u = subject\_user(S) \land subject\_roles(s_1, S) \cap RoleSet \neq \emptyset \land |OpSet| \geq 2 \Rightarrow OpSet \not\subseteq access history(s_0, s_1, u, RoleSet, obj) \cup \{op\}\}.
```

The following theorem shows that, for all SoD properties except the Object-based Dynamic SoD and History-based Dynamic SoD, if the start state of a command sequence satisfies the state invariants of the SoD property, then the command sequence satisfies the SoD property. (The proofs of all theorems of this paper are included in the Appendix.)

**Theorem 1.** Let App be an application in a secure RBAC system, and P one of the following SoD-P properties based on  $App: 1sSSSoD, SSSoD, SSoD, DSoD, RObjSSoD, ObjSSoD, ROpSSoD, OpSSoD, OpDSoD. Let <math>s_0 \in STATES_0$ , and  $\sigma \in \Sigma_0$  starting in  $s_0$ . If  $\hat{s}_0 \in P$  then  $\sigma \in P$ . As a corollary, if  $\hat{s}_0 \in P$  for all  $s_0 \in STATES_0$ , then  $P = \Sigma_0$ .

The following two theorems express the Object- and History-based Dynamic SoD properties by equivalent, more intuitive properties:

**Theorem 2.** Let App=[ObjSet, OpSet] be an application in a secure RBAC system, RoleSet its assigned roles, and  $\sigma \in \Sigma_0$ .  $\sigma \in ObjDSoD(RoleSet, App)$  if and only if all distinct operations in OpSet performed in states of  $\sigma$  on the same object of ObjSet in roles of RoleSet were performed by distinct users.

**Theorem 3.** Let App=[ObjSet, OpSet] be an application in a secure RBAC system, RoleSet its assigned roles, and  $\sigma \in \Sigma_0$ . The following statements are equivalent:  $1. \sigma \in HDSoD(RoleSet, App)$ ;

2. if  $\sigma$  executes App, then the operations of App (i.e., the operations in OpSet on objects in ObjSet performed in roles in RoleSet) are executed by at least two distinct users.

The definition of the wide variety of SoD properties above raises the question as to which policy to implement in a secure RBAC system, and which of the implemented policies to enforce in a given application. Although these questions cannot be answered independently of the application and system context, it is helpful to examine the relationships among these properties and property composability independent of their context of use. These relationships help in making the choice between implementing a stronger property, or a set of composable properties, instead of a more flexible property that may be harder to implement or administer. For example, one may choose to implement either Object-based Static SoD or the composition of per-Role Object-based Static SoD and Dynamic SoD, instead of Object-based Dynamic SoD (viz., Figure 1).

The following two theorems summarize the relationships among, and composability of, the SoD properties defined in this section.

**Theorem 4.** Let App be an application and RoleSet its assigned roles in a secure RBAC system. Assume that, in each start state, the set  $role\_members(r)$  of each role  $r \in RoleSet$  is not empty. Then the following properties hold:

- 1.  $lsSSSoD(RoleSet, App) \Rightarrow SSSoD(RoleSet, App)$ .
- $2.1sSSSoD(RoleSet, App) \Rightarrow ObjSSoD(RoleSet, App).$
- 3.  $lsSSSoD(RoleSet, App) \Rightarrow OpSSoD(RoleSet, App)$ .
- 4.  $SSSoD(RoleSet, App) \Rightarrow SSoD(RoleSet, App)$ .
- 5.  $SSoD(RoleSet, App) \Rightarrow DSoD(RoleSet, App)$ .
- 6.  $ObjSSoD(RoleSet, App) \Rightarrow RObjSSoD(RoleSet, App);$
- 7.  $SSoD(RoleSet, App) \Rightarrow$

 $(ObjSSoD(RoleSet, App) \Leftrightarrow RObjSSoD(RoleSet, App)).$ 

- 8.  $RObjSSoD(RoleSet, App) \land DSoD(RoleSet, App) \Rightarrow ObjDSoD(RoleSet, App)$ .
- 9.  $ObjSSoD(RoleSet, App) \Rightarrow ObjDSoD(RoleSet, App)$ .
- 10.  $OpSSoD(RoleSet, App) \Rightarrow ROpSSoD(RoleSet, App);$
- 11.  $SSoD(RoleSet, App) \Rightarrow$   $(OpSSoD(RoleSet, App) \Leftrightarrow$ ROpSSoD(RoleSet, App)).
- 12.  $ROpSSoD(RoleSet, App) \land DSoD(RoleSet, App) \Rightarrow OpDSoD(RoleSet, App)$ .
- 13.  $OpSSoD(RoleSet, App) \Rightarrow OpDSoD(RoleSet, App)$ .
- 14.  $ObjDSoD(RoleSet, App) \Rightarrow HDSoD(RoleSet, App)$ .
- 15.  $OpDSoD(RoleSet, App) \Rightarrow HDSoD(RoleSet, App)$ .

Figure 1 illustrates the relationships among SoD properties. To define property composition, let  $App_1$ ,  $App_2$  be two applications in a secure RBAC system, and  $RoleSet_1$ ,  $RoleSet_2$  their assigned roles, and let  $P_1 = P_1(RoleSet_1, App_1)$  and  $P_2 = P_2(RoleSet_2, App_2)$  be any two of the SoD properties defined in this section.

**Definition.** We say that properties  $P_1$  and  $P_2$  are composable if  $P_1 \cap P_2 \neq \emptyset$  whenever  $P_1 \neq \emptyset$  and  $P_2 \neq \emptyset$ .

If  $P_1$  and  $P_2$  are composable, then  $P_1^{\circ}P_2$  denotes their composition. As a predicate,  $P_1^{\circ}P_2 = P_1 \wedge P_2$ , and as a set of command sequences,  $P_1^{\circ}P_2 = P_1 \cap P_2$ .

**Theorem 5.** In a secure RBAC system that has:

- (1) arbitrary start states,  $STATES_0 = STATES$ , any two SoD properties are composable;
- (2) constrained start states,  $STATES_0 \subseteq STATES$ , the SoD properties are not necessarily composable.
- (3) a single start state,  $|STATES_0| = 1$ , any two SoD properties are composable.

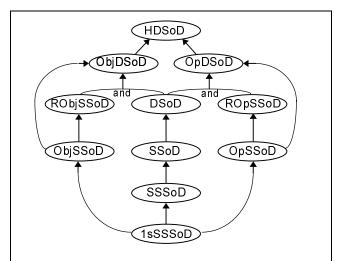


Figure 1. Relationships among SoD Properties

The composition of SoD properties is, actually, a conjunction of predicates, and an intersection of sets. Hence, the following relations hold for any set of start states and any SoD properties P, Q, R:

**Idempotency**. P is composable with itself, and  $P \circ P = P$ .

**Monotonicity.** If P is composable with Q, then  $P \circ Q \Rightarrow P$ .

**Commutativity**. If *P* is composable with *Q*, then *Q* is composable with *P* and  $P \circ Q = Q \circ P$ .

**Strengthening.** If  $P \Rightarrow Q$ , P is composable with R, and Q is composable with R, then  $P^{\circ}R \Rightarrow Q^{\circ}R$ . Note that the composability of P with R does not lead to the composability of Q with R (unless  $P \neq \emptyset$ ).

**Associativity**. If P is composable with Q,  $P^{\circ}Q$  is composable with R, Q is composable with R, and P is composable with  $Q^{\circ}R$ , then  $(P^{\circ}Q)^{\circ}R = P^{\circ}(Q^{\circ}R)$ . Note that the composability of P with Q and of  $P^{\circ}Q$  with R does not lead to the composability of Q with R (unless  $P \neq \emptyset$ ).

# **5** A Simple Composition Criterion

In this section, we define a simple composition criterion for SoD policies in RBAC systems and illustrate the use of the criterion with two examples.

In Section 2.2, we defined an SoD policy as follows:  $SoD - P = SoD - P \land Admin(SoD - P) \land Compat(SoD - P, App)$ 

1 RBAC-P

where  $\mathcal{RBAC-P} = RBAC-P \land Admin(RBAC-P)$ , and both SoD-P and RBAC-P are conjunctions of AT, AM, and AA properties. Since we assumed that all SoD policies are implemented in secure RBAC systems,  $\mathcal{RBAC-P}$  is satisfied and, hence,

 $SoD-P = SoD-P \land Admin(SoD-P) \land Compat(SoD-P, App)$ , where Admin(SoD-P) and Compat(SoD-P, App) are defined as follows:

**Definition.** Compat(SoD-P, App) is satisfied if and only if  $SoD-P \cap App \neq \emptyset$ ; i.e., SoD-P includes at least a command sequence that executes the application App.

Example 2 below shows that, unless Compat(P, App) is satisfied, composition of two policies cannot guarantee application executability. Hence, omitting Compat(P, App) can cause policies which otherwise are not composable to appear to be composable.

**Definition.** Admin(SoD-P) is satisfied if and only if  $\forall s \in STATES$ ,  $\exists s_0 \in STATES_0$ ,  $\exists \omega \in \Omega$  such that  $\omega$  starts in  $s \land \omega$  reaches  $s_0 \land \hat{s}_0 \in SoD-P$ ; i.e., starting in an arbitrary state, the administrative commands have the ability to bring the system in a state that satisfies property  $SoD-P^2$ .

A variant of Admin(SoD-P) might require that any state  $s_0 \in STATES_0$  such that  $\hat{s}_0 \in SoD-P$  be reachable from any other state.

Note that the predicate " $\omega$  reaches  $s_0$ " of Admin(SoD-P) is not trivially satisfied; e.g., the system may not provide all the administrative commands to ensure that certain states of  $STATES_0$  can be reached.

As a set, SoD-P = SoD-P whenever Admin(SoD-P) and Compat(SoD-P, App) are satisfied, and  $\emptyset$  otherwise. Whether Admin(SoD-P) and Compat(SoD-P, App) are satisfied requires the analysis of both command and application code.

Let  $App_1$  and  $App_2$  be two applications of a secure system, and let  $\mathcal{P}_1 = P_1 \wedge Admin(P_1) \wedge Compat(P_1, App_1)$ ,  $\mathcal{P}_2 = P_2 \wedge Admin(P_2) \wedge Compat(P_2, App_2)$  be two SoD policies for applications  $App_1$  and  $App_2$ .

**Definition**. Let  $\mathcal{P}_1 \circ \mathcal{P}_2$  be the SoD policy  $(P_1 \wedge P_2) \wedge Admin(P_1 \wedge P_2) \wedge Compat(P_1 \wedge P_2, App_1 \sqcup App_2)$ . We say that

 $\mathcal{P}_1$  is composable with  $\mathcal{P}_2$  if and only if  $\mathcal{P}_1^{\circ}\mathcal{P}_2 \neq \emptyset$  whenever  $\mathcal{P}_1 \neq \emptyset$  and  $\mathcal{P}_2 \neq \emptyset$ . Hence,

 $\mathcal{P}_1$  is composable with  $\mathcal{P}_2 \Leftrightarrow$ 

 $(\exists \sigma_1 \in P_1: \sigma_1 \text{ executes } App_1 \land Admin(P_1) \land$ 

 $\exists \sigma_2 \in P_2$ :  $\sigma_2$  executes  $App_2 \land Admin(P_2) \Rightarrow$ 

 $\exists \sigma \in P_1 \cap P_2$ :  $\sigma$  executes  $App_1, App_2 \wedge Admin(P_1 \wedge P_2)$ ).

If  $\mathcal{P}_1$  is composable with  $\mathcal{P}_2$ , then  $\mathcal{P}_1^{\circ}\mathcal{P}_2$  is called the *composition* of  $\mathcal{P}_1$  with  $\mathcal{P}_2$  or the *emerging policy*, and the set command sequences is  $\mathcal{P}_1 \cap \mathcal{P}_2$ .

The following properties of composition hold: *Idempotency*: any policy  $\mathcal{P}$  is composable with itself, and  $\mathcal{P}^{\circ}\mathcal{P} = \mathcal{P}$ .

Commutativity: for any two policies,  $\mathcal{P}_1$  and  $\mathcal{P}_2$ , if  $\mathcal{P}_1$  is composable with  $\mathcal{P}_2$ , then  $\mathcal{P}_2$  is composable with  $\mathcal{P}_1$  and  $\mathcal{P}_1^{\circ}\mathcal{P}_2 = \mathcal{P}_2^{\circ}\mathcal{P}_1$ .

*Monotonicity*: for any two policies  $\mathcal{P}_1$  and  $\mathcal{P}_2$ , if  $\mathcal{P}_1$  is composable with  $\mathcal{P}_2$ , then  $\mathcal{P}_1^{\circ}\mathcal{P}_2 \Rightarrow \mathcal{P}_1$ .

Associativity: for any three policies,  $\mathcal{P}_1$ ,  $\mathcal{P}_2$ ,  $\mathcal{P}_3$ , if  $\mathcal{P}_1$  is composable with  $\mathcal{P}_2$ ,  $\mathcal{P}_1^{\circ}\mathcal{P}_2$  is composable with  $\mathcal{P}_3$ ,  $\mathcal{P}_2$  is composable with  $\mathcal{P}_3$ , and  $\mathcal{P}_1$  is composable with  $\mathcal{P}_2^{\circ}\mathcal{P}_3$ , then  $(\mathcal{P}_1^{\circ}\mathcal{P}_2)^{\circ}\mathcal{P}_3 = \mathcal{P}_1^{\circ}(\mathcal{P}_2^{\circ}\mathcal{P}_3)$ .

**Theorem 6.** Let  $App_1$  and  $App_2$  be two applications of a secure system with  $STATES_0 = STATES$ , and  $\mathcal{P}_1 = P_1 \land Admin(P_1) \land Compat(P_1, App_1)$ ,  $\mathcal{P}_2 = P_2 \land Admin(P_2) \land Compat(P_2, App_2)$  two SoD policies. If the applications  $App_1$  and  $App_2$  do not share roles, operations, or objects, then the policies  $\mathcal{P}_1$  and  $\mathcal{P}_2$  are composable.

In the following two examples we illustrate the use of the composition criterion. We show that not all SoD policies are composable despite the fact that their SoD-P properties are composable. For simplicity, we assume that the properties  $Admin(P_1)$ ,  $Admin(P_2)$ , and  $Admin(P_1 \land P_2)$ , where  $P_1$  and  $P_2$  are the two SoD-P properties, are satisfied in both examples.

**Example 1.** Let  $poApp = \{\{purchase-order\},\}$ {read/write, sign, verify-sign}, poPlan] be a "purchaseorder processing" application, partitioned according to the plan poPlan = {(purchase-order, read/write), (purchaseorder, sign), (purchase-order, verify-sign). The user assignments of this application allow a purchase order clerk, but no other user, to write and sign purchase orders, and purchase orders become valid documents only after they are countersigned by an approving authority. Within the RBAC system, the roles of the purchase-order clerk and that of the approval authority are separated and the users are assigned accordingly; i.e., the operations read/write and sign purchase orders are executed by a role  $r_1$ , and verify-sign purchase orders is executed by a role  $r_2$ . Furthermore, the purchase order clerk and the approval authority may not be the same user, and hence, different users are enrolled in  $r_1$  and  $r_2$ .

<sup>&</sup>lt;sup>2</sup> We note that Admin(SoD-P) and Compat(SoD-P, App) are not properties of individual command sequences. Hence, they are neither "safety" nor "liveness" properties in the sense of Alpern and Schneider [2], and not subject to the Abadi-Lamport composition principle [1].

The following property specifies both the role assignments and the desired SoD property:  $poP = \\ (\forall s \text{ state of } \sigma, \forall r \in ROLES, r \neq r_1, r \neq r_2 \Rightarrow \\ execute \notin auth(s,r,poApp)) \land \\ (\forall s \text{ state of } \sigma, verify\_sign \notin auth(s,r_1,purchase\_order)$ 

 $\land$  read / write  $\notin$  auth(s,  $r_2$ , purchase\_order)  $\land$  sign  $\notin$  auth(s,  $r_2$ , purchase\_order))  $\land$  SSoD( $\{r_1, r_2\}$ , poApp).

Property poP is compatible with poApp, and consequently the policy  $\mathcal{P}_1 = poP \land Compat(poP, poApp)$  is not empty. The administrator has to grant the permissions read/write, sign to the role  $r_1$ , and verify-sign to  $r_2$ , and to assign two different users to roles  $r_1$  and  $r_2$ .

Let  $apApp = [\{purchase-order, check\}, \{read, \}]$ read/write, sign, apPlan be an "accounts payable" application, partitioned according to the plan apPlan = {(purchase-order, read), (check, read/write), (check, sign). The user assignments of this application allow a clerk, but no other user, to read purchase orders and write checks, but the checks must be signed by another user who has signature authority. Within the RBAC system, the roles of the clerk who writes checks and that of the checksigning authority are separated accordingly; i.e., the operations read purchase orders and read/write checks are executed by a role  $r_3$ , and sign checks are executed by a role  $r_4$ . Furthermore, the clerk and the signature authority must not be the same user, and hence, different users are enrolled in  $r_3$  and  $r_4$ . The following property specifies both the role assignments and the desired SoD property:

```
(\forall s \text{ state of } \sigma, \forall r \in ROLES, r \neq r_3, r \neq r_4 \Rightarrow execute \notin auth(s, r, apApp)) \land \\ (\forall s \text{ state } \forall s \text{ state of } \sigma, sign \notin auth(s, r_3, check)) \land \\ (\forall s \text{ state of } \sigma, read \notin auth(s, r_4, purchase\_order)) \land \\ (\forall s \text{ state of } \sigma, read \mid write \notin auth(s, r_4, check)) \land \\ ObjDSoD(\{r_3, r_4\}, apApp).
```

Property apP is compatible with apApp, and consequently the policy  $\mathcal{P}_2 = apP \wedge Compat(apP, apApp)$  is not empty. The administrator has to grant the permissions read purchase orders, read/write checks to the role  $r_3$ , and sign checks to  $r_4$ , and assign two different users to roles  $r_3$  and  $r_4$ .

Obviously, the policies  $\mathcal{P}_1$  and  $\mathcal{P}_2$  are composable under the composability criteria defined in this section: there are tranquil command sequences that execute both applications and satisfy both poP and apP.

**Example 2.** Let's define  $\mathcal{P}_1$  as in Example 1, and let  $cpApp = [\{purchase-order\}, \{read/write, sign\}, cpPlan]$  be a "central purchasing" application, partitioned

according to the plan is  $cpPlan = \{(purchase-order, read), (purchase-order, read/write), (purchase-order, sign)\}$ . The user assignments of this application require that the reading of the departmental purchase orders and the writing of organization purchase orders be separated from the signing of organization purchase order. Thus, in the RBAC system, the first two operations and the last operation of the plan are executed by separate roles  $r_1$  and  $r_5$ . The following property specifies the role assignments and the desired SoD property:  $cpP = \frac{r_1 + r_2}{r_1}$ 

 $(\forall s \text{ state of } \sigma, \forall r \in ROLES, r \neq r_1, r \neq r_5 \Rightarrow execute \notin auth(s, r, cpApp)) \land (\forall s \text{ state of } \sigma, read / write \notin auth(s, r_5, purchase\_order)) \land OpSSoD(\{r_1, r_5\}, cpApp).$ 

Property cpP is compatible with cpApp, and consequently the policy  $\mathcal{P}_3 = cpP \wedge Compat(cpP, cpApp)$  is not empty. The administrator has only to grant read/write permissions to  $r_1$  and sign permission to  $r_5$  (and, of course, to have users assigned to these roles).

Policies  $\mathcal{P}_1$  and  $\mathcal{P}_3$  are *not* composable. To satisfy the OpSSoD property of policy  $\mathcal{P}_3$ ,  $\sigma$  must start in a state such that  $r_1$  does not have the sign permission. Such a tranquil command sequence could never execute poApp, because  $r_1$  requires the sign permission by virtue of policy  $\mathcal{P}_1$ .

We note that the administrator can *redefine* policies  $\mathcal{P}_1$  and  $\mathcal{P}_3$  to obtain policies  $\mathcal{P}_1$ ' and  $\mathcal{P}_3$ ', which are composable. This can be done by making either one of the following changes via *non-tranquil* commands:

- add a new role in  $\mathcal{P}_1$  and grant the *sign* permission to it and, at the same time, remove the *sign* permission from  $r_1$ ; or
- replace  $r_1$  in  $\mathcal{P}_3$  with a new role that has only *read/write* permissions.

Note that, had we defined the above SoD policies only via SoD-P properties, all the policies would have appeared to be composable. However, Example 2 above shows that, when compatibility is taken into account, two of the SoD policies become incompatible and, hence, not composable.

### 6 Conclusions

The use of formalism in the definition of SoD properties helps (1) identify a wide variety of such properties, (2) remove ambiguities from informal definitions, and (3) establish heretofore unknown relationships among these properties. Formal SoD policies were also defined using the SoD properties.

The variety of SoD properties, while offering a wide choice of implementation, suggests that new

administrative methods and tools are necessary if these properties are to be effectively used. This is the case even for RBAC systems, which offer significant support for implementing SoD properties.

#### Acknowledgments

This paper was funded in part by the US Department of Commerce, National Oceanographic and Atmospheric Administration, under the SBIR Contract No. 50-DKNB-7-90120. The views expressed herein are those of the authors and do not necessarily reflect the views of the US Department of Commerce or any of its sub-agencies. The first author would like to thank C. Sekar Chandersekaran of IBM Corporation for his interest in, and support of, this work. We also thank John McLean for his helpful comments.

### References

- [1] Abadi M., and L. Lamport, "Composing specifications," Stepwise refinement of Distributed Systems, J. W. de Bakker, W. P. de Roever, and G. Rosenberg, eds., Lecture Notes in Computer Science, vol. 430, Springer-Verlag, 1990.
- [2] Alpern B., and F. Schneider, "Defining liveness," Information Processing Letters, vol. 21, no. 4, Oct. 1985, pp. 181-185.
- [3] Clark D. D., and D. R. Wilson, "A Comparison of Commercial and Military Security Policies," Proc. of the 1987 IEEE Symposium on Security and Privacy, Oakland, California, 1987, pp. 184-194.
- [4] Clark D. D., and D. R. Wilson, "Evolution of a Model for Computer Integrity," in *Report of the Invitational Workshop on Data Integrity*, Z.G. Ruthberg and W.T. Polk (eds.), NIST Special Publication 500-168, Appendix A, September 1989.
- [5] Common Criteria for Information Technology Security Evaluation, GISA, NNCSA, CESG, NIST, NSA, Version 2.0 Draft, December 1997.
- [6] Federal Criteria for Information Technology Security, Vol. 1, Chapter 3 and Appendix C, Version 1.0, NIST and NSA, December 1992.
- [7] Ferraiolo D., J. Cugini, and D. R. Kuhn, "Role-Based Access Control (RBAC): Features and Motivations," Proc. 1995 Computer Security Applications Conference, December 1995, pp. 241-248.
- [8] Gligor, V. D., S. I. Gavrila, and J. Cugini, "The RBAC Security Policy Model", http://cspa09.ncsl.nist.gov/disk2/ rbac/docs/model.ps
- [9] Hecht, M. S., M. E. Carson, C. S. Chandersekaran, R. S. Chapman, L. J. Dotterer, V. D. Gligor, W. D. Jiang, A. Johri, G. L. Luckenbaugh, and N. Vasudevan, "Unix Without the Superuser," Proc. of the 1987 USENIX Conference, Phoenix, Arizona, June 1987, pp. 243-256.
- [10] Hummel, A. A., K. Deinhart, S. Lorenz, V. D. Gligor, "Role-Based Security Administration," *Sicherheit in*

- *Informationsystemen* (K. Bauknecht, D. Karagiannis, and S. Teufel (eds.)), vdf Hochschulverlag, ETH Zurich, March 1996, pp. 69-92.
- [11] Kailar R., V. D. Gligor, and L. Gong, "Security Effectiveness of Cryptographic Protocols," in *Dependable* Computing for Critical Applications - 4, F. Cristian, G. LeLann, and T. Lunt (eds.), Springer Verlag, 1995, pp. 139-157.
- [12] Koch, G., and K. Loney, Oracle. The complete reference, Oracle Press, 1995.
- [13] Nash M. J., and K. R. Poland, "Some Conundrums Concerning Separation of Duty," Proc. 1990 IEEE Symposium on Security and Privacy, Oakland, California, May 1990, pp. 201-207.
- [14] Sandhu, R., "Transaction Control Expressions for Separation of Duties," Proc. of the 4th Aerospace Computer Security Conference, Tucson, Arizona, Dec. 1988, pp. 282-286.
- [15] Simon R. T., and M. E. Zurko, "Separation of Duty in Role-Based Environments," Proc. of Computer Security Foundations Workshop X, Rockport, Massachusetts, June 1997.
- [16] Trusted Recovery Guideline, NCSC-TG-022, Version 1, National Computer Security Center, December, 1989.
- [17] Unified INFOSEC Criteria, INFOSEC Concepts, Section 3, "Dependencies among TCSEC Requirements (unclassified)", National Security Agency, 1993.

# **Appendix: Proofs**

**Proof of Theorem 1.** We prove the theorem for the SSoD property. The proofs for the other properties are similar, and, for simplicity, are omitted. Note first that the SSoD property is a state property, and that all other state and transition properties are RBAC specific, and are satisfied in the secure RBAC system. Let  $\sigma$  be  $op_1(s_0, S_1, obj_1, s_1) \cdot op_2(s_1, S_2, obj_2, s_2) \cdot \dots$  We know that  $s_0$  satisfies the SSoD property. Suppose that  $s_n$ , where  $n \ge 0$ , satisfies SSoD, and that  $s_{n+1}$  does not. This implies that there are two roles  $r_1$ ,  $r_2$ , sharing a common user u in state  $s_{n+1}$ . There are two possible cases:

- a)  $r_1$  and  $r_2$  had the common user in state  $s_n$ ;
- b) the command  $op(s_n, S_{n+1}, obj_{n+1}, s_{n+1})$  created or updated  $r_1$  or  $r_2$ ;

Case a) is rejected by the inductive hypothesis, and case b) is contradicted by  $\sigma$  being tranquil. Hence,  $s_{n+1}$  satisfies SSoD.

**Proof of Theorem 2.** Let  $\sigma$  be in ObjDSoD(RoleSet, App), and let  $\sigma$  start in  $s_0$ . When a user u performs two distinct operations,  $op_1$ ,  $op_2 \in OpSet$  on an object  $obj \in ObjSet$ , in roles of RoleSet and in states of  $\sigma$ , the system reaches a state s of  $\sigma$  such that  $\{op_1, op_2\} \subseteq access\_history(s_0, s, u, RoleSet, obj)$ . But ObjDSoD and the  $access\_history$  properties imply that  $access\_history(s_0, s, u, RoleSet, obj) \subset \{op_1\}$  and, hence,  $\{op_1, op_2\} \subset \{op_1\}$ ,

contradiction. Conversely, assume, by way of contradiction, that  $\sigma \notin ObjDSoD$ . Then there is a state s in  $\sigma$  such that  $access\_history(s_0, s, u, RoleSet, obj) \supseteq \{op_1, op_2\}$ , where u is a user,  $obj \in ObjSet$ ,  $op_1$ ,  $op_2 \in OpSet$ . This means that u has performed two distinct operations on the same object of App.

**Proof of Theorem 3.** Similar to the proof of Theorem 2.

#### Proof of Theorem 4.

- 1. This is a consequence of the two SoD definitions.
- 2. The *IsSSSoD* property says that *RoleSet* has no roles with common role members, so that a *RoleSubset* in the *ObjSSoD* condition is reduced to a single role. Also by *ssSSoD*, that role is authorized to at most one operation of *OpSet*.
- 3. As before, the 1sSSSoD property reduces a RoleSubset with common role members to a single role, which is authorized to perform at most one operation of OpSet. Consequently, OpSet with a cardinality of at least 2 cannot be a subset of the authorized permissions of that single role.
- 4. This is a consequence of the two SoD definitions.
- 5. The roles enabled (active) for a user must be among those assigned to that user. Thus, if two roles have no common members, they cannot have common active users.
- 6. Let r be a role in RoleSet,  $op_1 \neq op_2$  two operations in OpSet, and obj in ObjSet. If we apply the ObjSSoD property to  $RoleSubset = \{r\}$ , we get as a conclusion  $\{op_1, op_2\} \nsubseteq \bigcup_{x \in RoleSubset} auth(s, x, obj) = auth(s, r, obj)$ .
- 7. Assuming that SSoD holds, we have to prove the converse of 6. Let RoleSubset be a subset of roles in RoleSet with common members. SSoD implies that RoleSubset is reduced to a single role. For such RoleSubset, the ObjSSoD and RObjSSoD conditions coincide.
- 8. Let  $\sigma$  be a command sequence starting in  $s_0$  and satisfying the RObjSSoD and DSoD properties, and  $op(s_1, S, obj, s_2)$  a command of  $\sigma$ , with  $r \in subject\_roles(s_1, S) \cap RoleSet \neq \emptyset$ ,  $obj \in ObjSet$ ,  $op \in OpSet$ . Assume, by way of contradiction, that there is a role  $r_1 \in RoleSet$  and an operation  $op_1 \in OpSet$ ,  $op_1 \neq op$ , such that  $op_1 \in access\_history(s_0, s_1, subject\_user(S), \{r_1\}, obj)$ . Either  $r = r_1$ , and this means that in a state s of s op, s op\_1 s auth(s, s, s, s, s which contradicts s active in both s and s in a state of s, which contradicts s s object\\_user(s) is active in both s and s in a state of s, which contradicts s s object\\_user(s).
- 9. Let  $\sigma$  be a command sequence starting in  $s_0$  and satisfying the ObjSSoD property, and  $op(s_1, S, obj, s_2)$  a command of  $\sigma$ , with  $r \in subject\_roles(s_1, S) \cap RoleSet \neq \emptyset$ ,  $obj \in ObjSet$ ,  $op \in OpSet$ . Assume, by way of contradiction,

that there is a role  $r_1 \in RoleSet$  and an operation  $op_1 \in OpSet$ ,  $op_1 \neq op$ , such that  $op_1 \in access\_history(s_0, s_1, subject\_user(S), \{r_1\}, obj)$ . We conclude that  $subject\_user(S) \in role\_members(r) \cap role\_members(r_1)$ , and  $\{op, op_1\} \subseteq auth(s_1, r, obj) \cup auth(s_1, r_1, obj)$ , which contradicts the ObjSSoD property.

10. Let  $\sigma$  be a command sequence satisfying the OpSSoD property. Let  $|OpSet| \ge 2$  and suppose by way of contradiction that there is a role  $r \in RoleSet$  and a state s of  $\sigma$  such that  $OpSet \subseteq \bigcup_{obj \in ObjSet} auth(s, r, obj)$ . Let us

choose  $RoleSubset = \{r\}$ . The preceding inclusion can be written as  $OpSet \subseteq \bigcup_{\substack{x \in RoleSubset \\ obj \in ObjSet}} auth(s, x, obj)$ , which

contradicts the *OpSSoD* property.

- 11. If  $\sigma$  satisfies the SSoD property, any RoleSubset with common members is reduced to a single role, and for such subsets the OpSSoD and ROpSSoD conditions are equivalent.
- 12. Let  $\sigma$  be a command sequence that satisfies the DSoD and ROpSSoD properties. Because of DSoD, any RoleSubset with common active users (as required by the OpDSoD property) is reduced to a single role, RoleSubset =  $\{r\}$ . The OpDSOD condition OpSet  $\nsubseteq\bigcup_{x\in RoleSubset} auth(s, x, obj)$  may be written OpSet opSet
- $\not\equiv \bigcup_{\substack{obj \in ObjSet}} auth(s, r, obj)$ , which is true by the ROpSSoD

#### property.

- 13. Let  $\sigma$  be a command sequence that satisfies the OpSSoD property, and RoleSubset a subset of RoleSet with common active users. Then RoleSubset also has common members. If we assume  $|OpSet| \ge 2$  and apply OpSSoD, we get exactly the conclusion of OpDSoD.
- 14. Let  $\sigma$  be a command sequence that starts in  $s_0$  and satisfies the ObjDSoD property,  $|OpSet| \ge 2$ , and  $op(s_1, S, obj, s_2)$  a command in  $\sigma$  with  $op \in OpSet$ ,  $obj \in ObjSet$ ,  $r \in subject\_roles(S) \cap RoleSet$ . Assume, by way of contradiction that  $OpSet \subseteq access\_history(s_0, s_1, u, RoleSet, obj) \cup \{op\}$ . There must be  $op_1 \in OpSet, op_1 \ne op$ , and  $r_1 \in RoleSet$ , such that  $op_1 \in access\_history(s_0, s_1, subject\_user(S), \{r_1\}, obj)$ , which contradicts the ObjDSoD property.
- 15. Let  $\sigma$  be a command sequence that starts in  $s_0$  and satisfies the OpDSoD property,  $|OpSet| \ge 2$ , and  $op(s_1, S, obj, s_2)$  a command of  $\sigma$  such that  $op \in OpSet$ ,  $obj \in ObjSet$ ,  $r \in subject\_roles(S) \cap RoleSet$ . Suppose by way of contradiction that  $OpSet \subseteq access\_history(s_0, s_1, subject\_user(S), RoleSet, obj) \cup \{op\}$ . But  $access\_history(s_0, s_1, subject\_user(S), RoleSet, obj) \subseteq \bigcup_{x \in RoleSet} auth(s_1, x, obj)$ , and  $op \in auth(s_1, r, obj)$ .

Consequently,  $OpSet \subseteq \bigcup_{x \in RoleSet} auth(s_1, x, obj)$ , which contradicts the OpDSoD property.

#### Proof of Theorem 5.

- (1) Let  $P_1$  and  $P_2$  be two SoD properties. If we can find a start state  $s_0$  satisfying the state invariants of both  $P_1$ and  $P_2$ , then clearly  $\hat{s}_0 \in P_1 \cap P_2$ . We note that if the roles assigned to an application satisfy a SoD property P, then after revoking a permission from one of the roles or removing a member from one of the roles, they still satisfy P. Now, starting in an arbitrary state with the current roles, and through possibly non-tranquil commands, we can revoke permissions one by one and/or remove members one by one from the  $App_1$ 's roles until we reach a state that satisfies  $P_1$ . It is always possible to do that, because the empty role (without permissions) with no members satisfies any SoD property. Then, we can apply the same procedure to App2's roles, until we reach a state that satisfies  $P_2$  (and  $P_1$ ). This new state, which satisfies both  $P_1$  and  $P_2$ , is the new start state.
- (2) Let  $App_1=[\{obj_1\}, \{op_1, op_2\}, plan_1],$   $App_2=[\{obj_2\}, \{op_3, op_4\}, plan_2]$  be two applications in a secure RBAC system, and  $RoleSet_1=\{r_1, r_2\}, RoleSet_2=\{r_3, r_4\}$  their assigned roles. Let  $STATES_0=\{s_0', s_0''\}$ , with the states  $s_0', s_0''$  such that:

- in  $s_0'$ ,  $r_1$  and  $r_2$  do not have common assigned users, and  $r_3$  has permissions  $op_3$ ,  $op_4$ ; and
- in  $s_0''$ ,  $r_1$  and  $r_2$  have a common assigned user, and  $r_3$  has only permission  $op_3$ , and  $r_4$  has only permission  $op_4$ .

Then,  $P_1$ = $SSoD(RoleSet_1, App_1)$  $\neq \emptyset$ ,  $P_2$ = $ROpSSoD(RoleSet_2, App_2)$  $\neq \emptyset$ , but  $P_1 \cap P_2 = \emptyset$ . Indeed, any tranquil command sequence starting in  $s_0$ ' satisfies  $P_1$  but not  $P_2$ , and any tranquil command sequence starting in  $s_0$ " satisfies  $P_2$  but not  $P_1$ .

(3)  $P_1$ = $SSoD(RoleSet_1, App_1) \neq \emptyset$  and  $P_2$ = $ROpSSoD(RoleSet_2, App_2) \neq \emptyset$  means that the start state  $s_0$  satisfies  $P_1 \land P_2$ . At least  $\hat{s}_0 \in P_1 \cap P_2$ .

**Proof of Theorem 6.** Suppose that  $\exists \sigma_1 \in P_1$ :  $\sigma_1$  executes  $App_1 \land \exists \sigma_2 \in P_2$ :  $\sigma_2$  executes  $App_2$ . Hence, there are start states  $s_0$ ' satisfying  $P_1$  and  $s_0$ " satisfying  $P_2$ . Then, starting from  $s_0$ ', for example, and using possibly nontranquil transitions, we can reach a state  $s_0$  satisfying both  $P_1$  and  $P_2$  (their constraints do not interfere). Taking  $s_0$  as start state, we can apply the commands of  $\sigma_1$  executing  $App_1$ , then the commands of  $\sigma_1$  executing  $App_2$ , which again do not interfere.